

A dataflow model of concurrency, communication and weak memory

John Wickerson & Tony Hoare

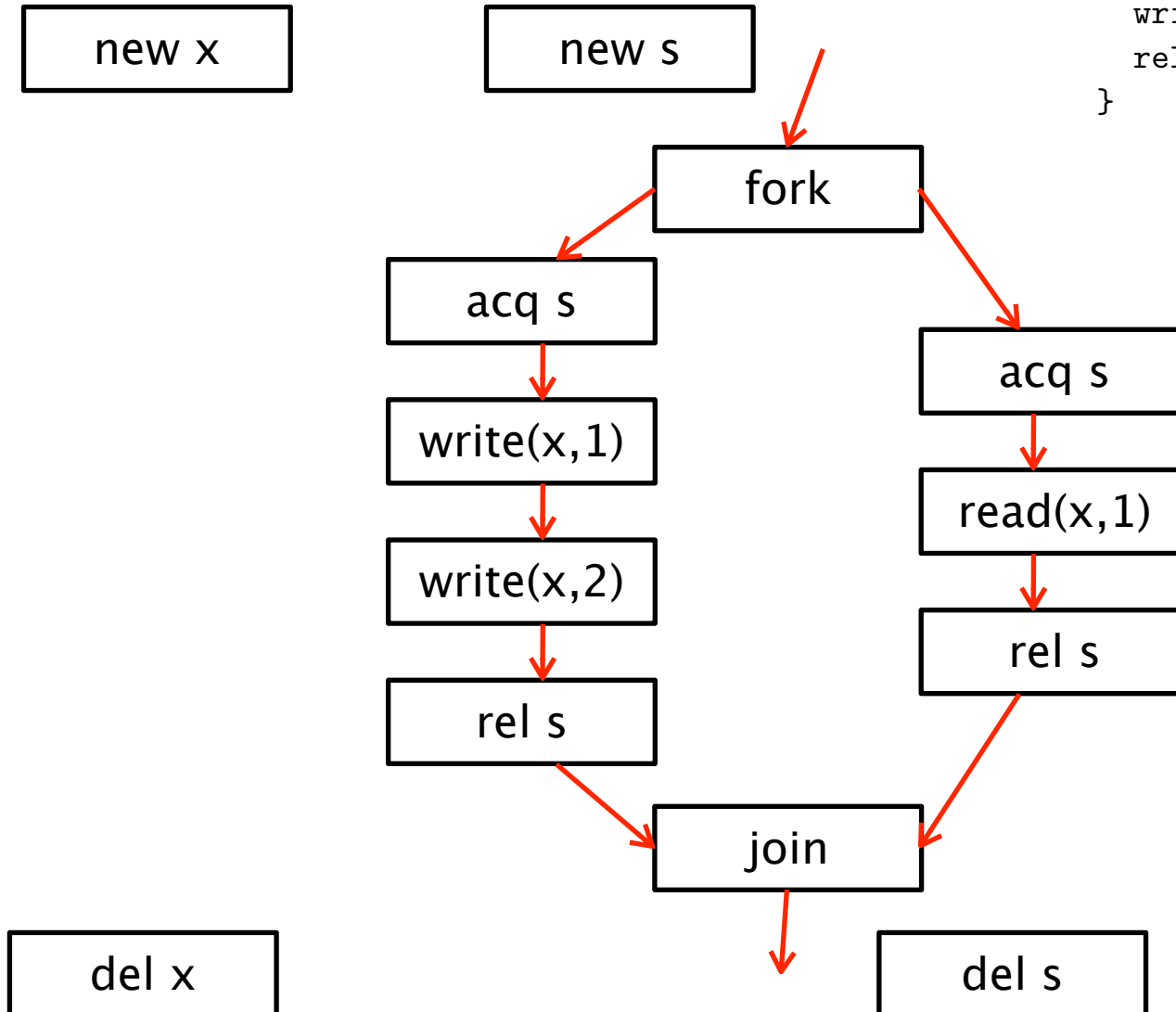


Example

```
lock s in var x in {  
    acq s;          || acq s;  
    write(x,1);    || read(x,1);  
    write(x,2);    || rel s  
    rel s          ||  
}
```

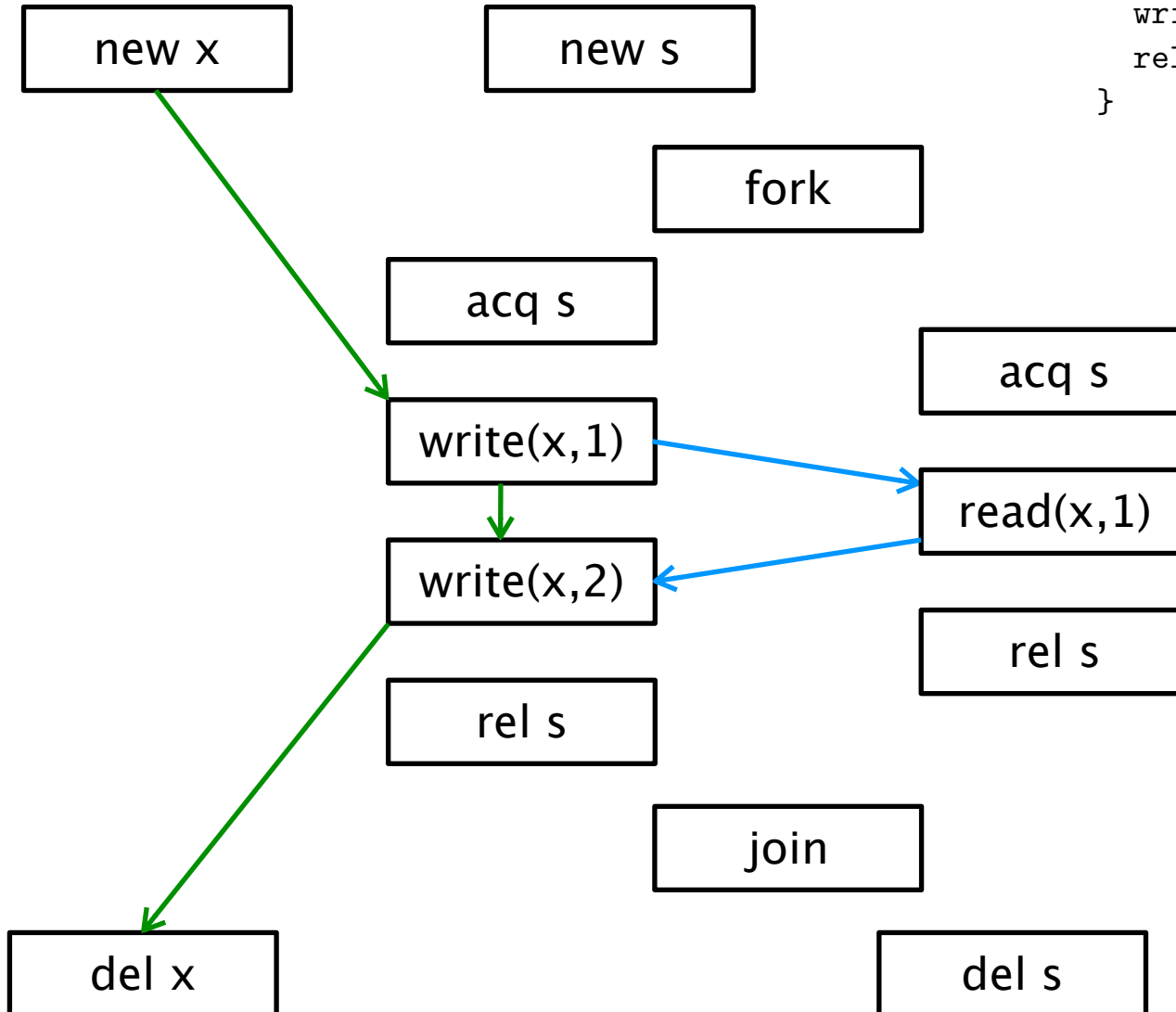
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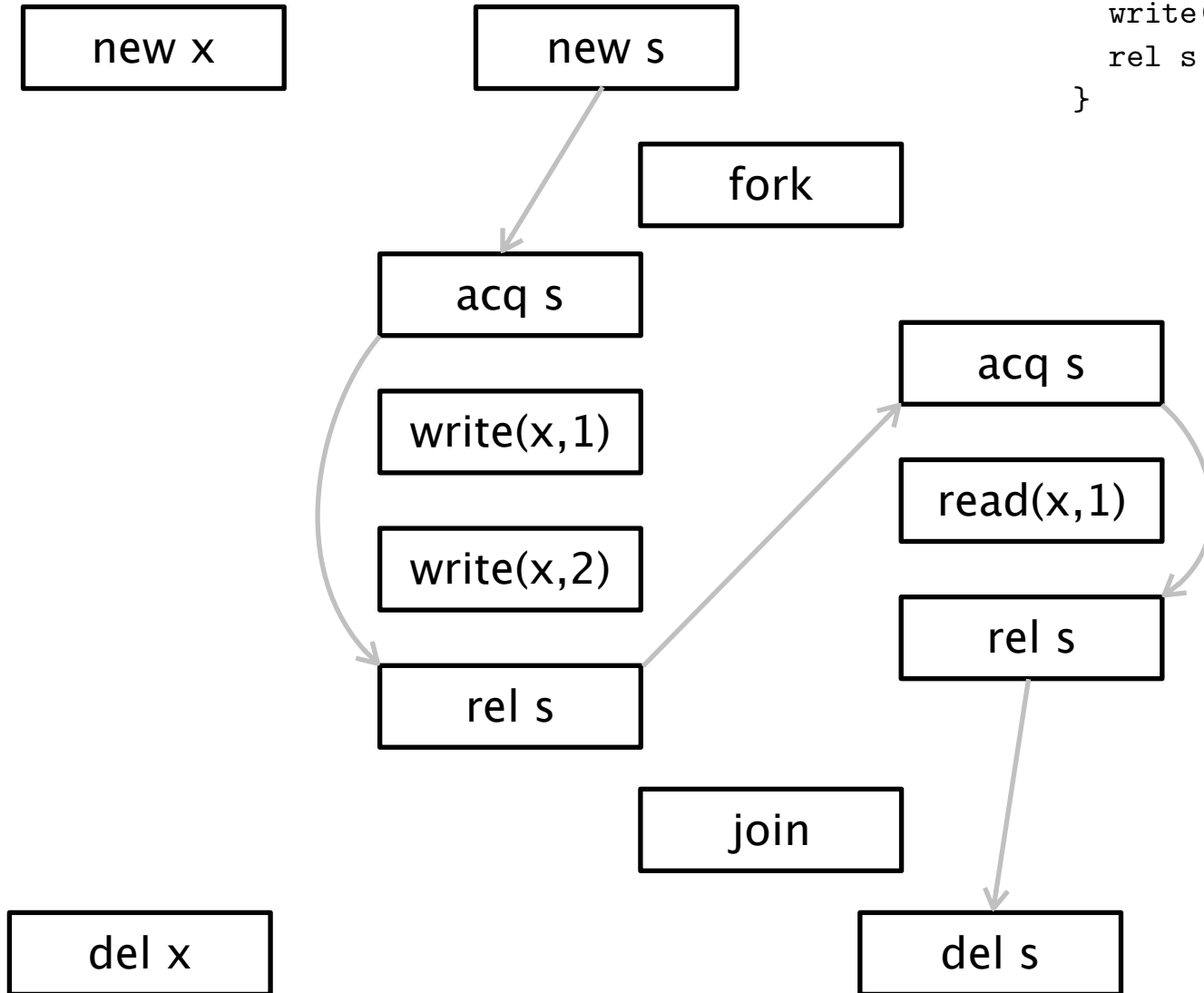
Example

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lock s in var x in {  
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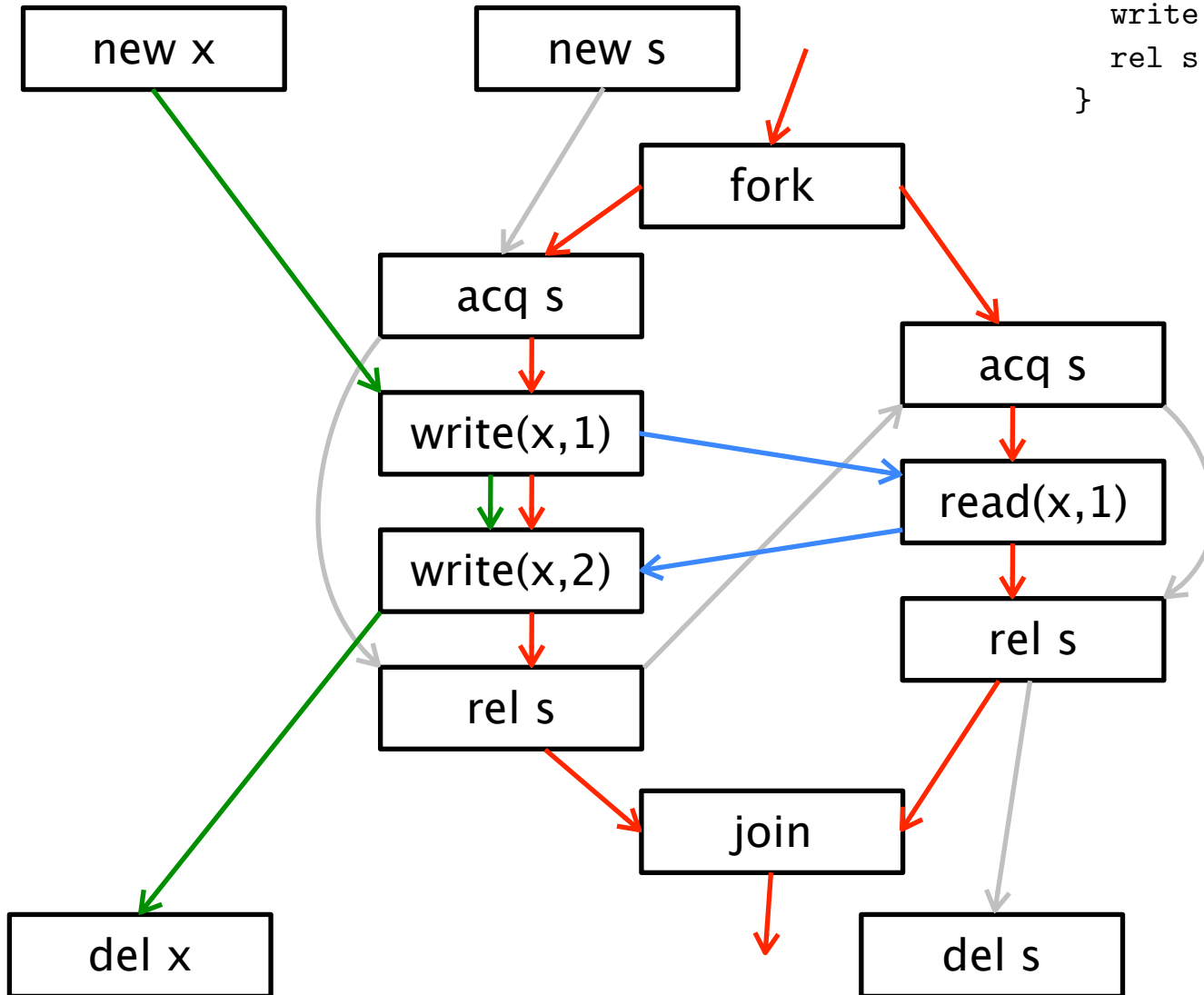
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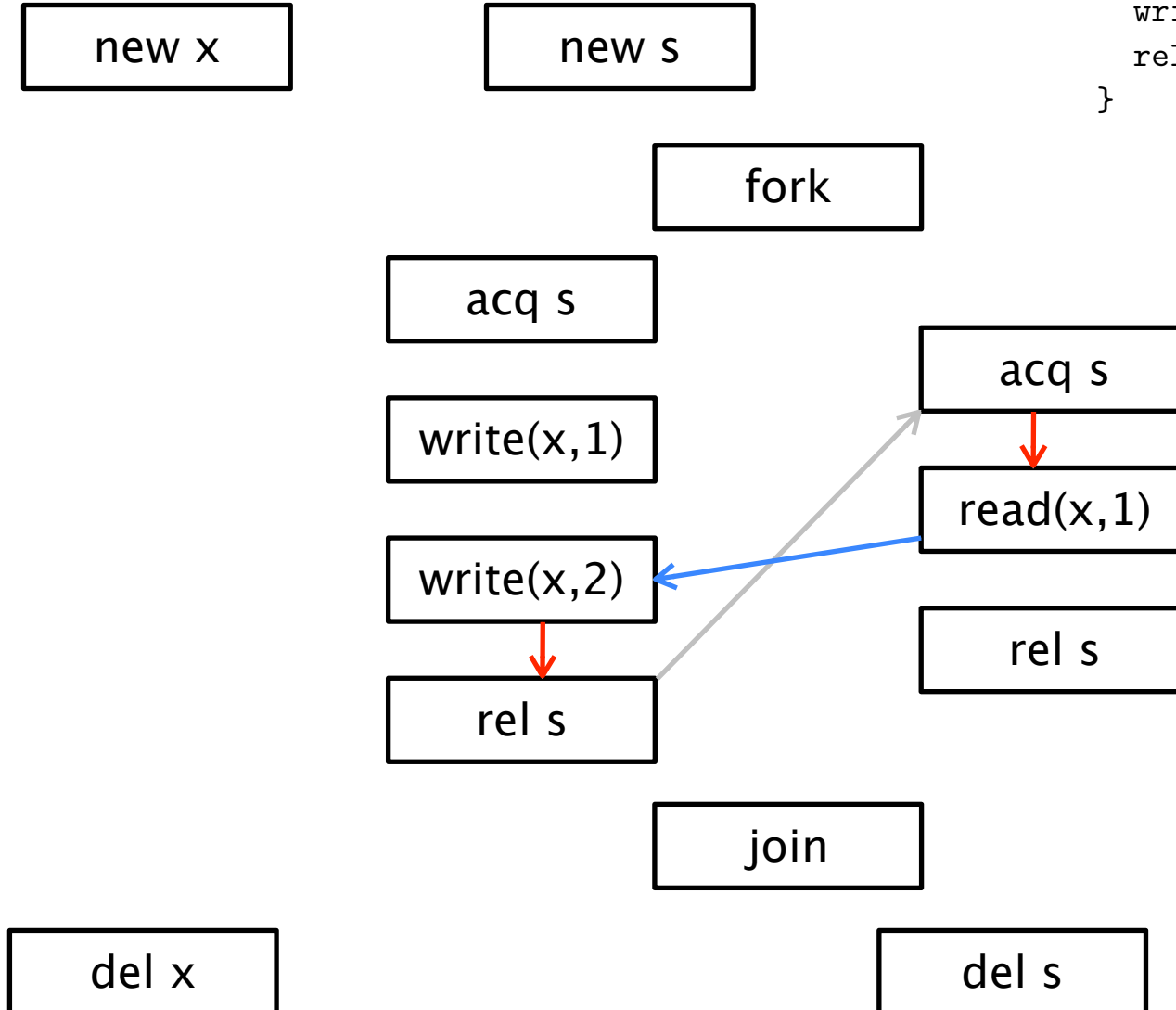
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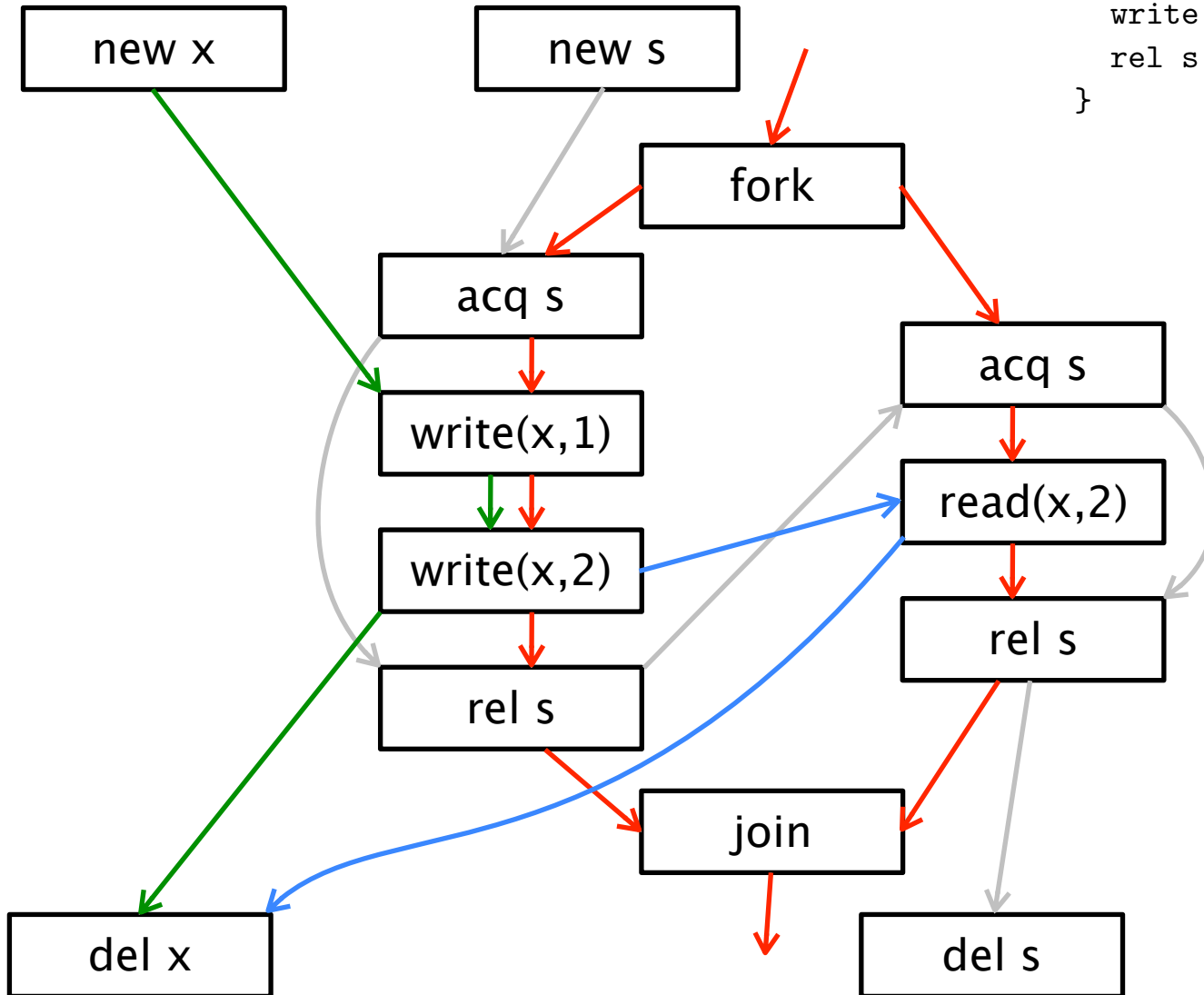
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Example

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lock s in var x in {  
  acq s;          || acq s;  
  write(x,1);    || read(x,2);  
  write(x,2);    || rel s  
  rel s          ||  
}
```



Outline

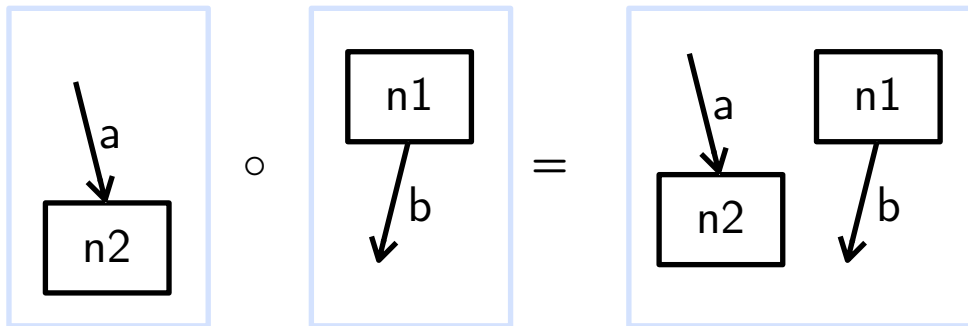
- We model a program as a set of possible traces
- We separate various kinds of flow
 - data flow, control flow, ownership transfer
- Our model is stateless
 - good for modelling weak memory and asynchronous communication

Traces

- Represented as a 6-tuple:
 - NodeSet, $N \in \mathbb{P}_{\text{fin}} \text{Node}$
 - ArrowSet, $A \in \mathbb{P}_{\text{fin}} \text{Arrow}$
 - Labelling, $L \in N \rightarrow \text{Label}$
 - Valuation, $V \in A \rightarrow \text{Value}$
 - HeadMap, $H \in A \rightarrow N$
 - TailMap, $T \in A \rightarrow N$

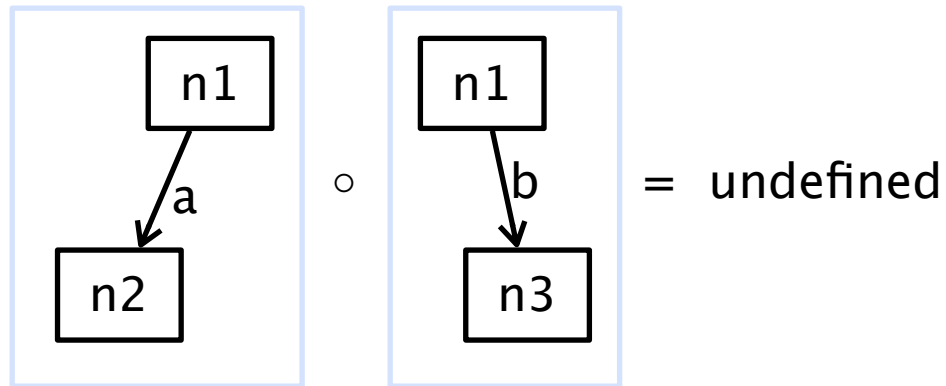
Traces

- A composition operator:



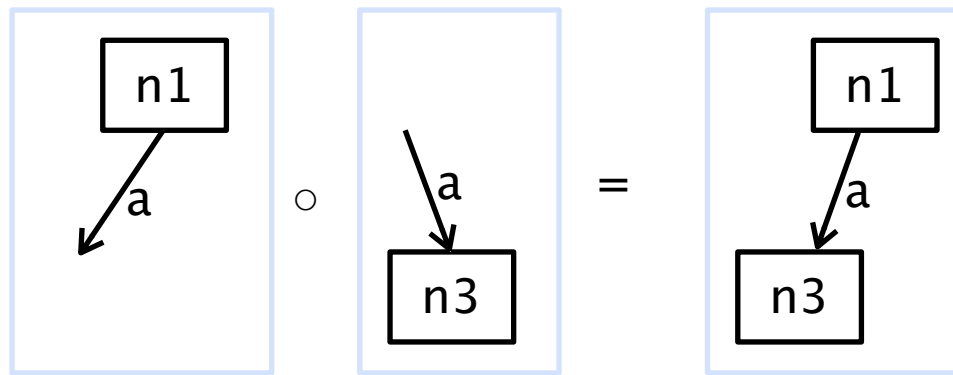
Traces

- A composition operator:



Traces

- A composition operator:



- Lifted to sets of traces:

$$T * U = \{t \circ u \mid t \in T, u \in U\}$$

A denotational semantics

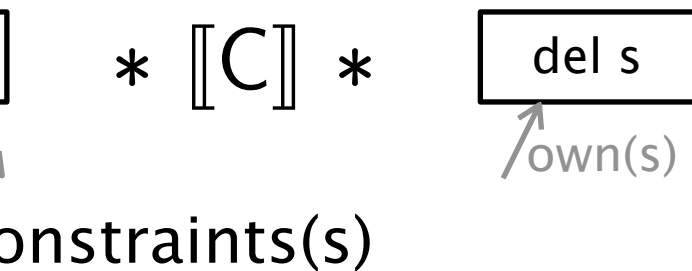
$$\llbracket - \rrbracket : \text{Command} \rightarrow \mathbb{P}_{\text{fin}}(\text{Trace})$$

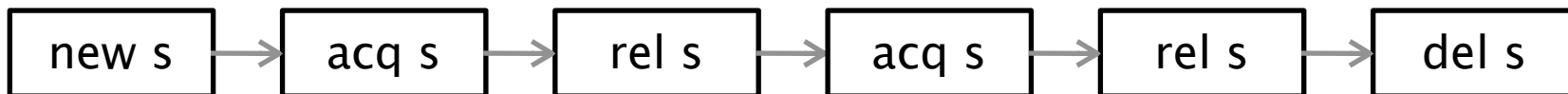
Locks

• $C ::= \dots \mid \text{lock } s \text{ in } C \mid \text{acq } s \mid \text{rel } s$

• $\llbracket \text{acq } s \rrbracket =$ 

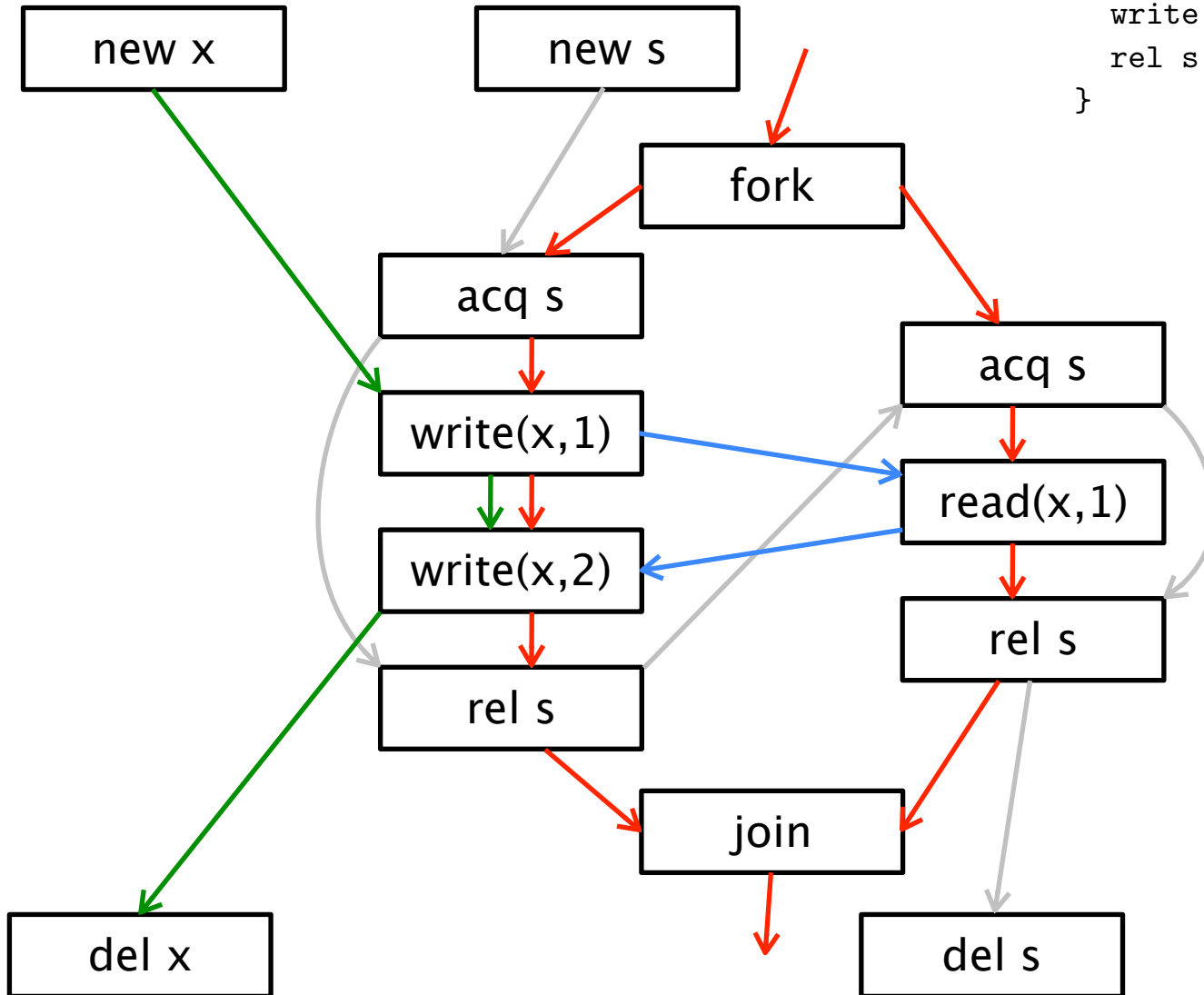
• $\llbracket \text{rel } s \rrbracket =$ 

• $\llbracket \text{lock } s \text{ in } C \rrbracket =$  $n \text{ lockconstraints}(s)$

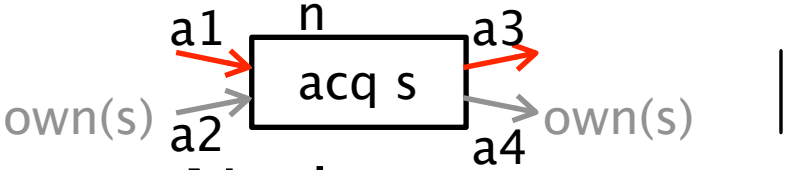


Example

```
lock s in var x in {  
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  write(x,1); || read(x,1);  
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  rel s      }  
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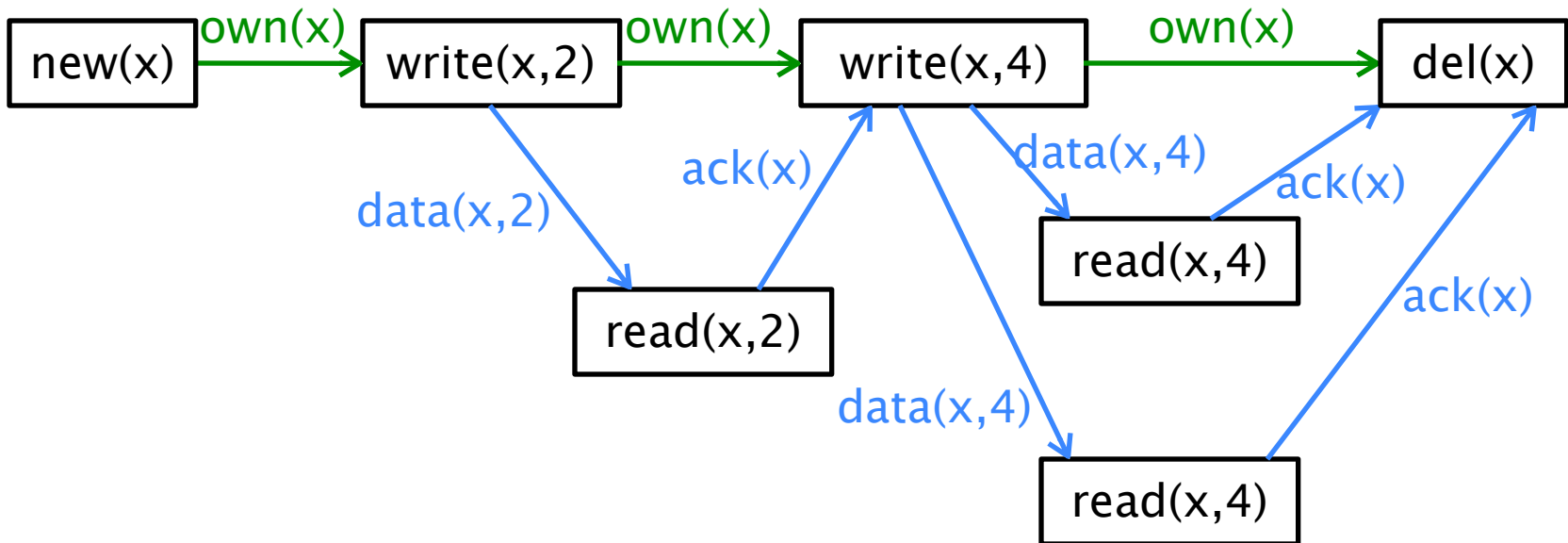
Locks

- $\llbracket \text{acq } s \rrbracket = \{$


$n \in \text{Node},$
 $a1, a2, a3, a4 \in \text{Arrow},$
 $a1, a2, a3, a4$ all distinct $\}$

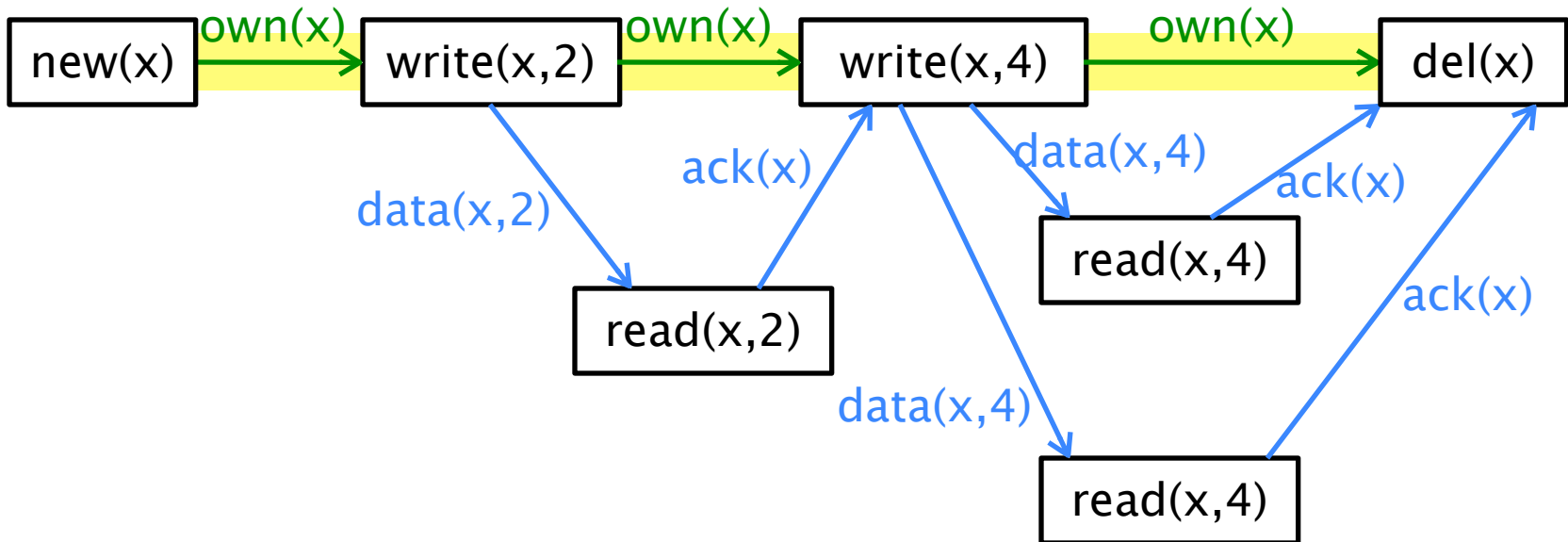
Variables

- $C ::= \dots \mid \text{var } x \text{ in } C \mid \text{write}(x,v) \mid \text{read}(x,v)$



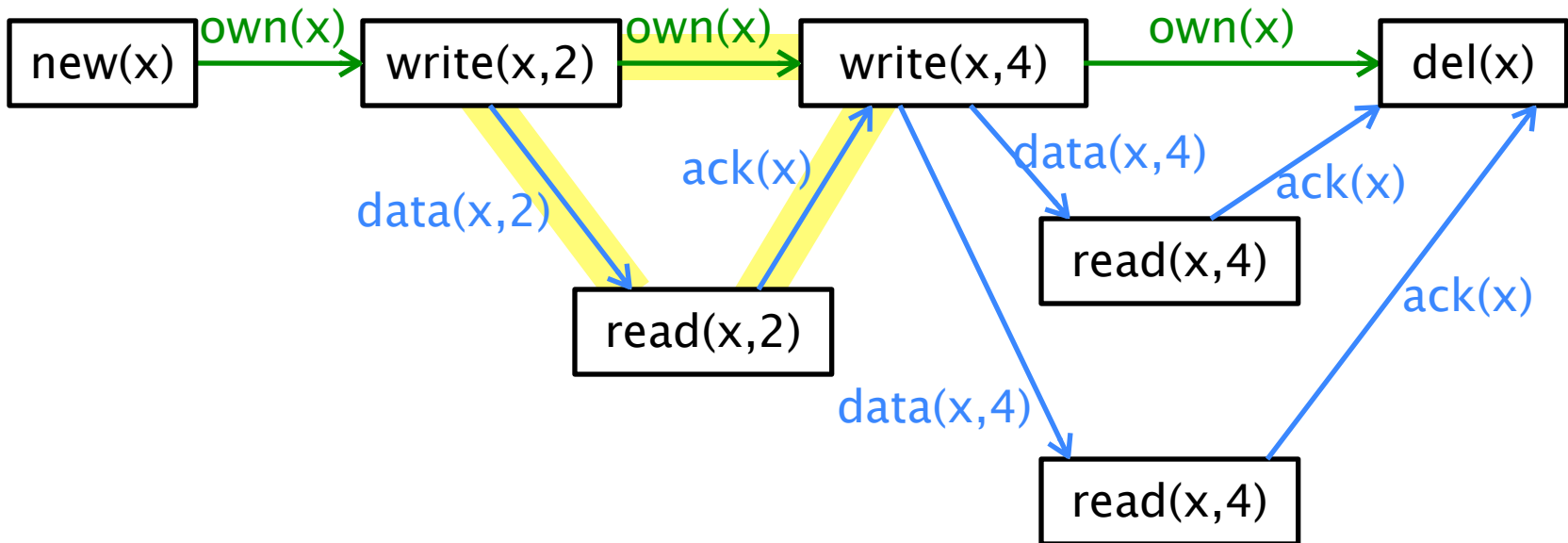
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Variables

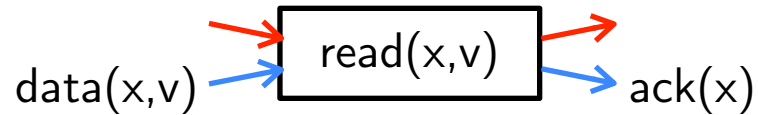
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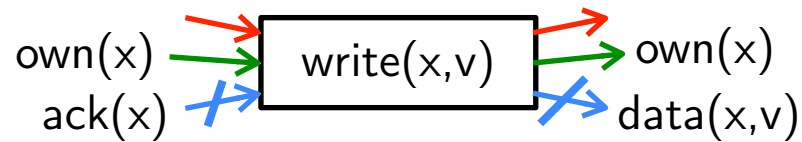
Variables

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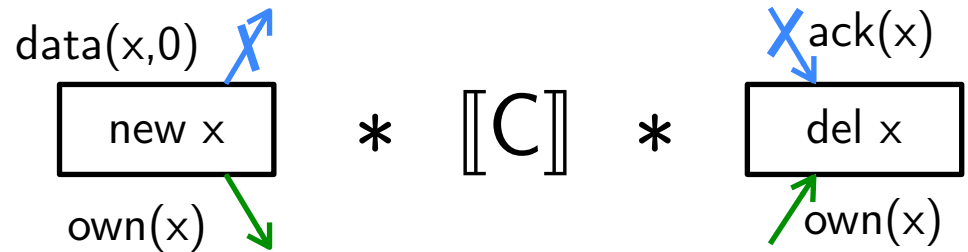
- $\llbracket \text{read}(x,v) \rrbracket =$



- $\llbracket \text{write}(x,v) \rrbracket =$



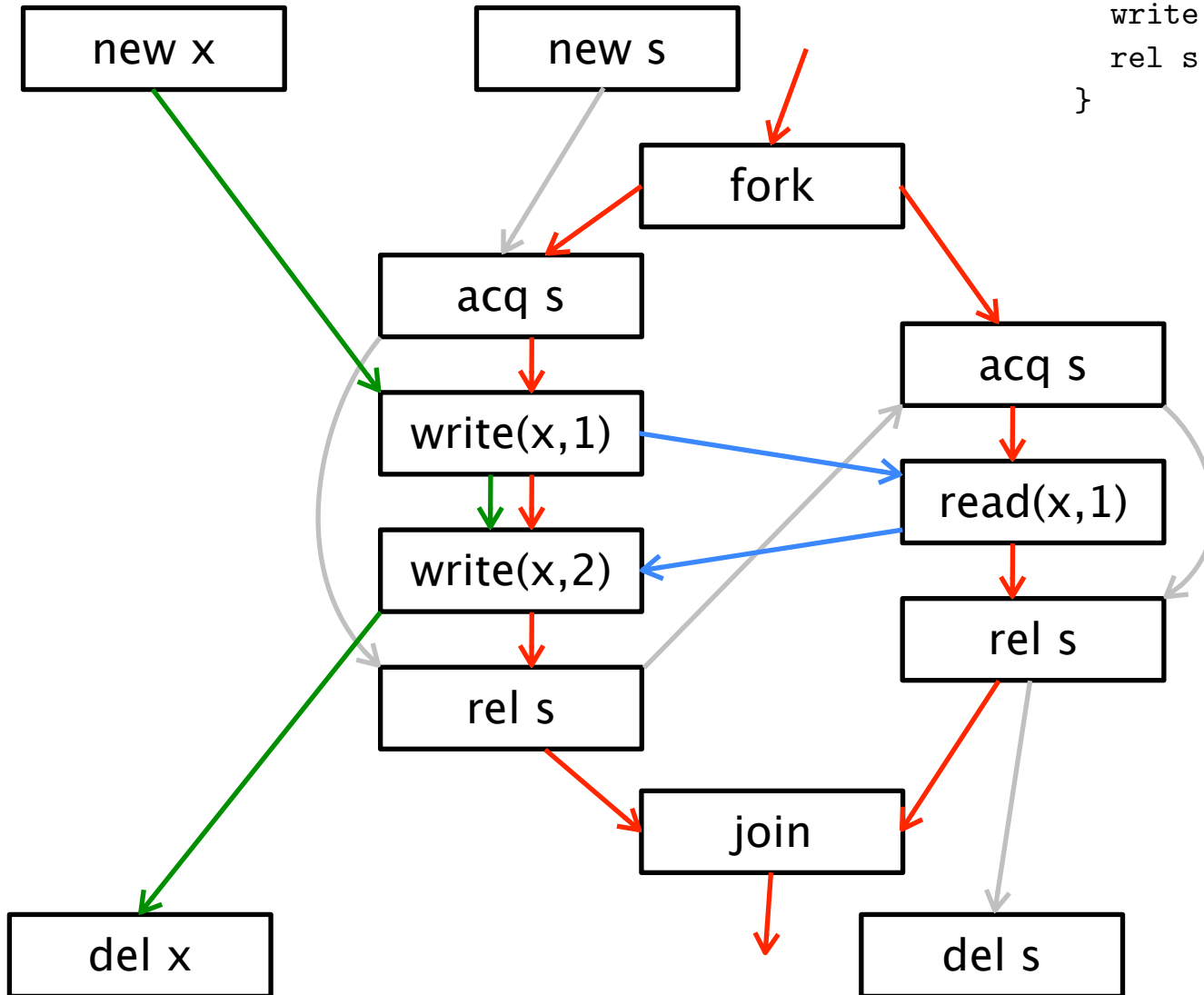
- $\llbracket \text{var } x \text{ in } C \rrbracket =$



$\cap \text{varconstraints}(x)$

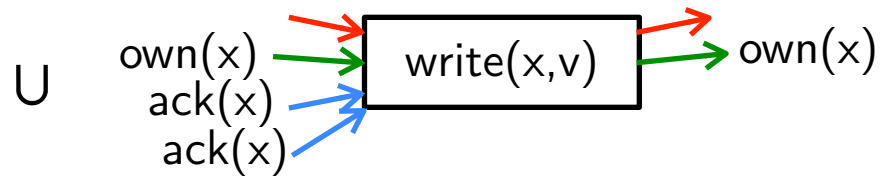
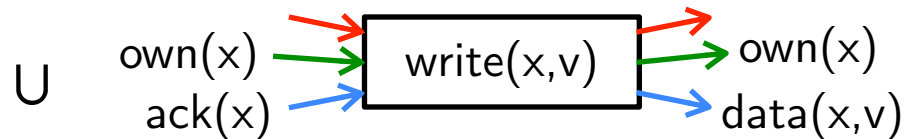
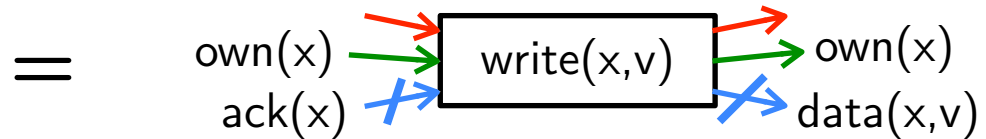
Example

```
lock s in var x in {  
  acq s;      || acq s;  
  write(x,1); || read(x,1);  
  write(x,2); || rel s  
  rel s      }  
}
```



Variables

- $\llbracket \text{write}(x,v) \rrbracket$



\cup ...

Assignments and assumptions

- $\llbracket x := f(y_1, \dots, y_n) \rrbracket =$
$$\cup \{ \llbracket \text{read}(y_1, v_1); \dots ; \text{read}(y_n, v_n); \text{write}(x, v) \rrbracket$$
$$\mid f(v_1, \dots, v_n) = v \}$$
- $\llbracket \text{assume } p(x_1, \dots, x_n) \rrbracket =$
$$\cup \{ \llbracket \text{read}(x_1, v_1); \dots ; \text{read}(x_n, v_n) \rrbracket$$
$$\mid p(v_1, \dots, v_n) = \text{true} \}$$

Sequential composition

- $\llbracket C_1; C_2 \rrbracket = \llbracket C_1 \rrbracket *_{\text{seq}} \llbracket C_2 \rrbracket$

where $t_1 \circ_{\text{seq}} t_2$ is only defined when:

$$\text{outCtrl}(t_1) = \text{inCtrl}(t_2)$$

and $*_{\text{seq}}$ is the lifted version of \circ_{seq}

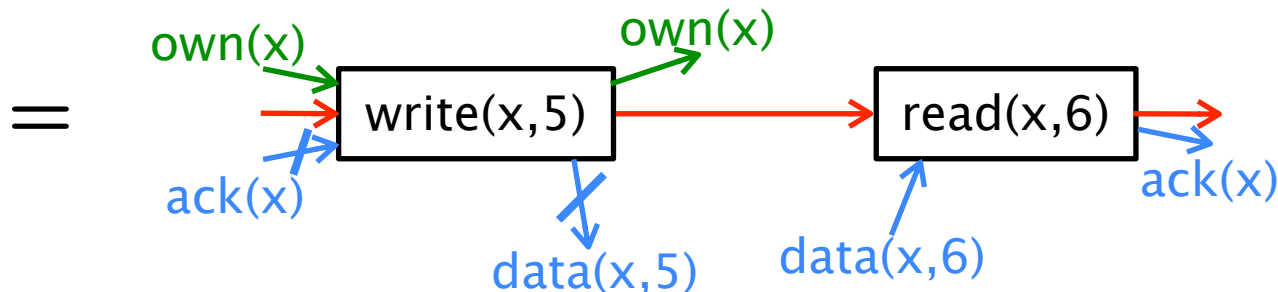
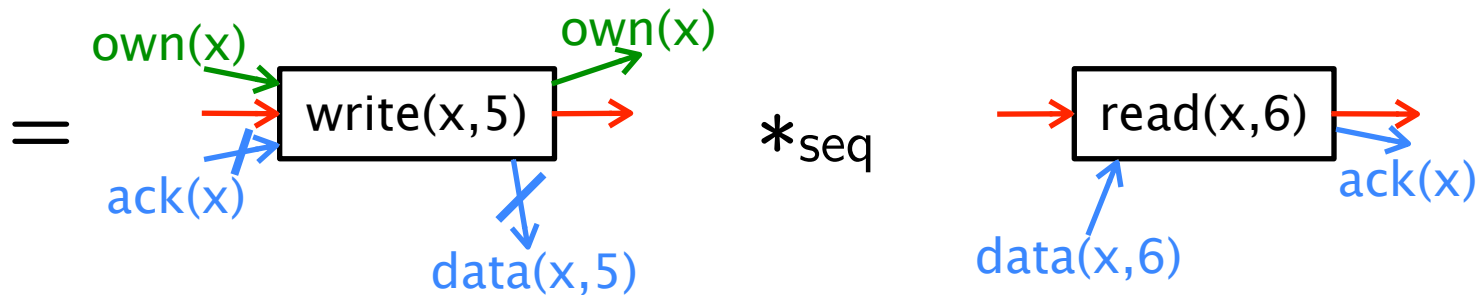
Sequential composition

- Examples:



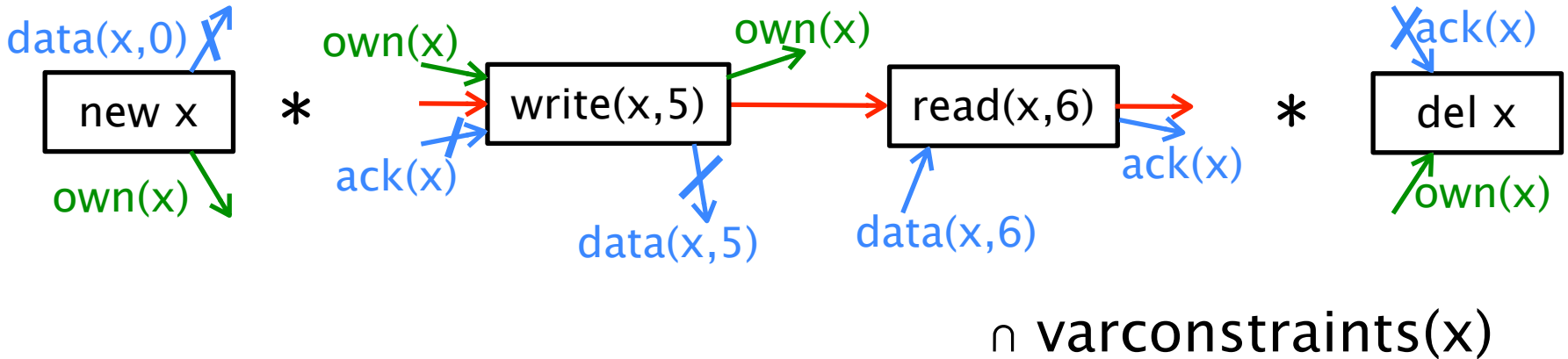
Sequential composition

- $\llbracket x:=5; \text{assume } x=6 \rrbracket$



Sequential composition

- $\llbracket \text{var } x \text{ in } \{x:=5; \text{assume } x=6\} \rrbracket =$



Parallel composition

- $\llbracket C_1 \parallel C_2 \rrbracket =$

$$\rightarrow \boxed{\text{fork}} \Rightarrow *_{\text{seq}} (\llbracket C_1 \rrbracket *_{\text{par}} \llbracket C_2 \rrbracket) *_{\text{seq}} \Rightarrow \boxed{\text{join}} \rightarrow$$

where $t_1 \circ_{\text{par}} t_2$ is only defined when:

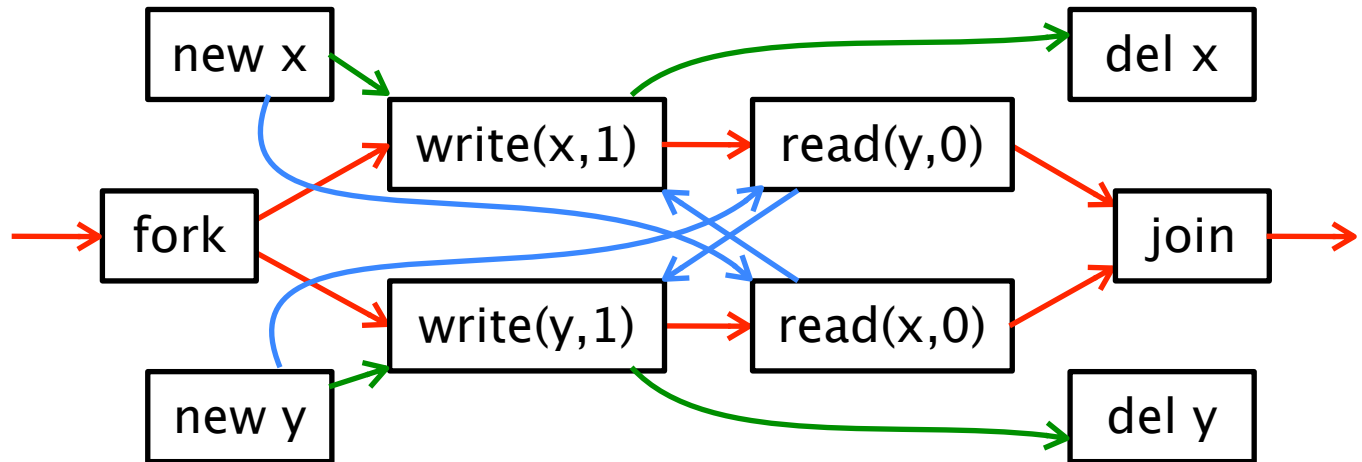
$$\text{danglingCtrl}(t_1) \cap \text{danglingCtrl}(t_2) = \emptyset$$

and $*_{\text{par}}$ is the lifted version of \circ_{par}

Weak memory

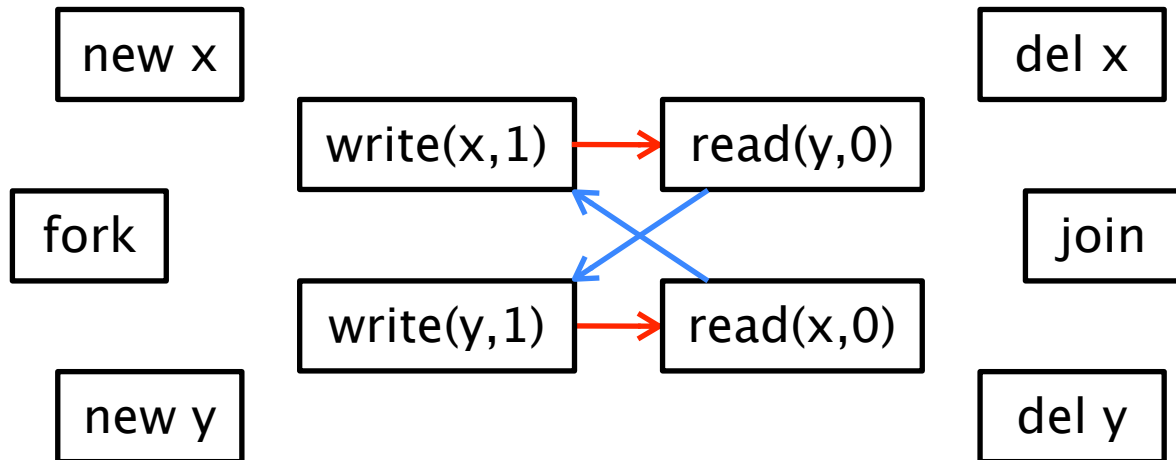
Weak memory

```
var x in var y in {  
  write(x,1); || write(y,1);  
  read(y,0)   || read(x,0)  
}
```

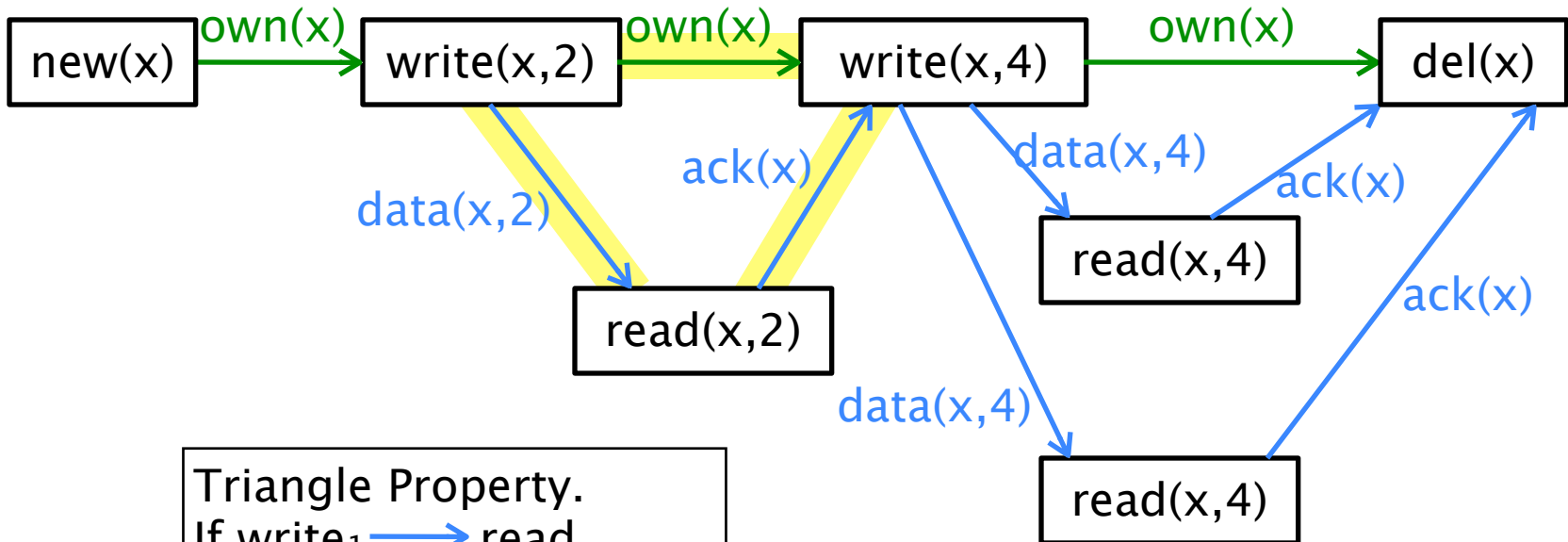


Weak memory

```
var x in var y in {  
  write(x,1); || write(y,1);  
  read(y,0)   || read(x,0)  
}
```

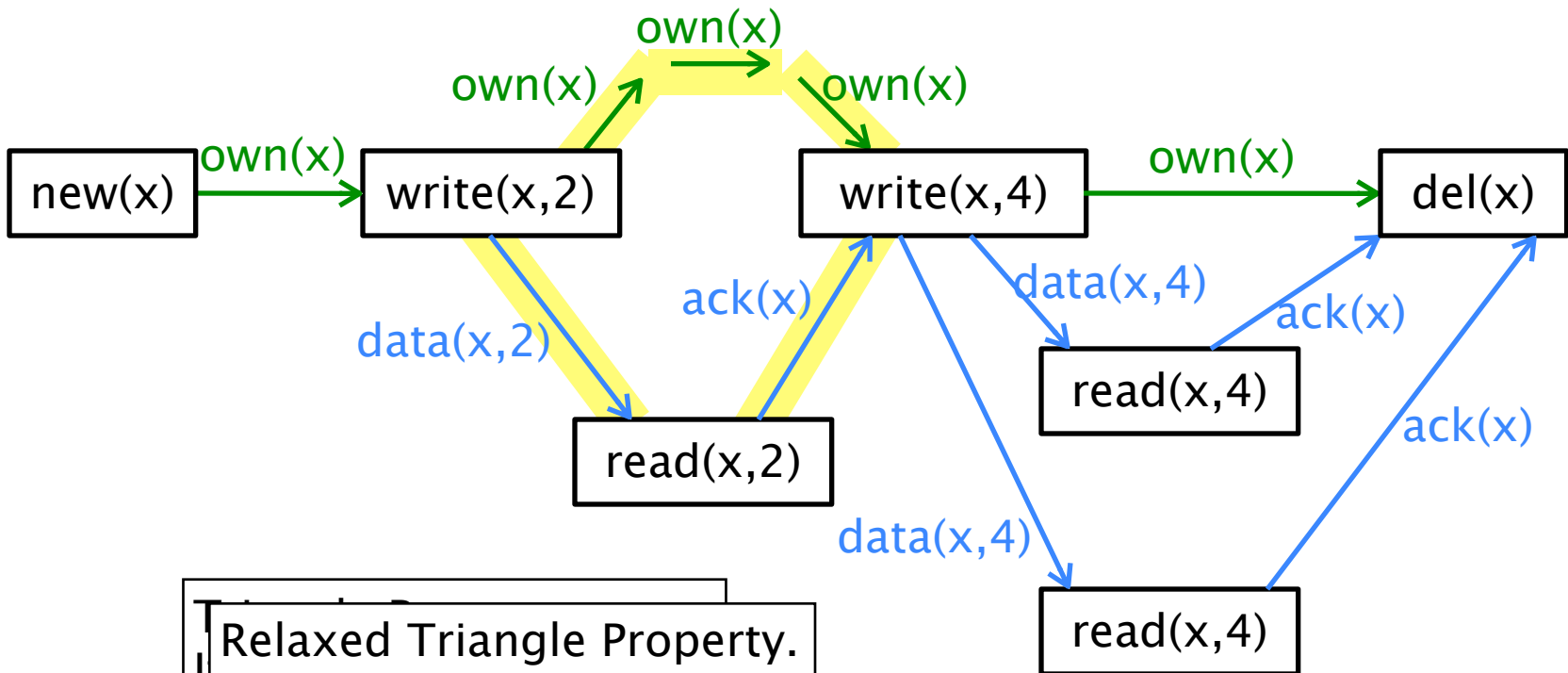


Variables



Triangle Property.
If $write_1 \rightarrow read$
and $read \rightarrow write_2$
then $write_1 \rightarrow write_2$

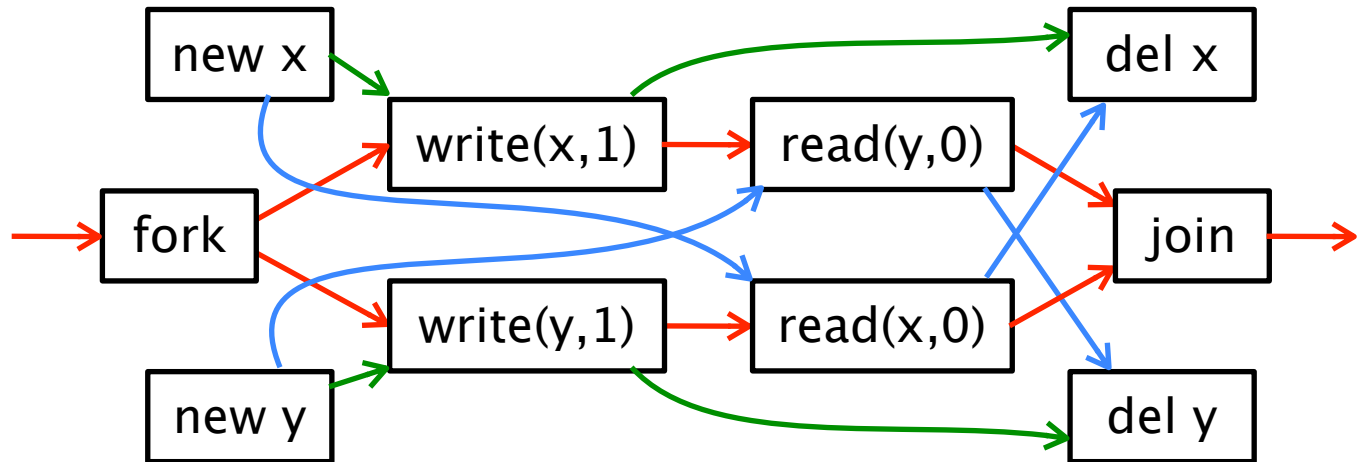
Variables



Relaxed Triangle Property.
If `write1` → `read`
and `read` → `write2`
then `write1` →⁺ `write2`

Weak memory

```
var x in var y in {  
  write(x,1); || write(y,1);  
  read(y,0)   || read(x,0)  
}
```



Summary

- A model of concurrency, communication and weak memory, based on dataflow
- Next steps:
 - automate the generation of traces?
 - use as a basis for a program logic for weak memory?

Spare slides

Use of separation logic laws

- We can use laws of separation logic to prove theorems about our model, such as commutativity of local variable declarations

Use of separation logic laws

- $\llbracket \text{var } x \text{ in } C \rrbracket = \boxed{\text{new } x} * \llbracket C \rrbracket * \boxed{\text{del } x}$

The diagram illustrates the decomposition of a variable declaration into its constituent parts and their associated memory constraints:

 - new x**: A box representing the allocation of memory for variable x . It is associated with the constraint $\text{data}(x,0)$ (pointing to the top) and $\text{own}(x)$ (pointing to the bottom).
 - $\llbracket C \rrbracket$** : The body of the variable declaration, which may use the memory allocated to x .
 - del x**: A box representing the deallocation of memory for variable x . It is associated with the constraint $\text{ack}(x)$ (pointing to the top) and $\text{own}(x)$ (pointing to the bottom).

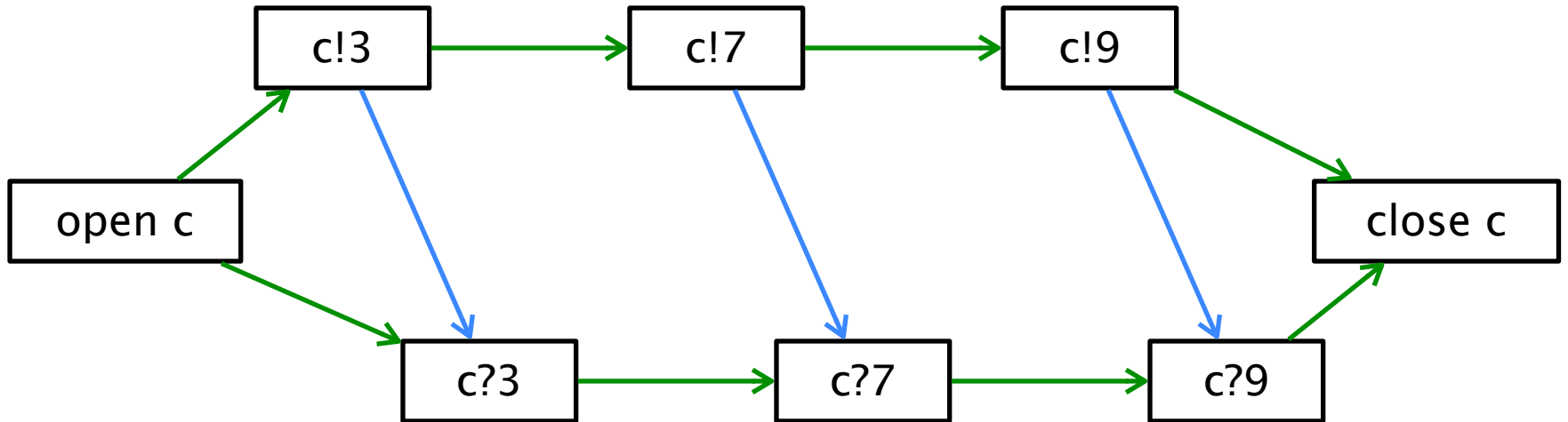
The overall expression is annotated with $\text{varconstraints}(x)$ at the bottom, indicating the total memory constraints for the variable x .

Use of separation logic laws

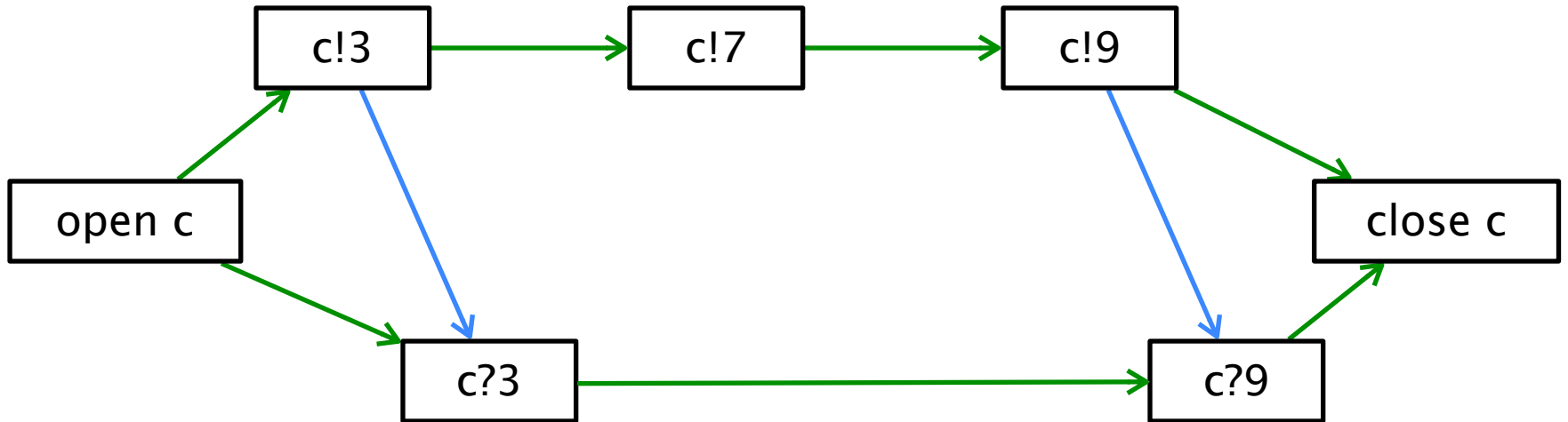
- $\llbracket \text{var } x \text{ in } C \rrbracket = (\llbracket C \rrbracket * \text{nd}_x) \cap v_x$
- $\llbracket \text{var } y \text{ in var } x \text{ in } C \rrbracket = \llbracket \text{var } x \text{ in var } y \text{ in } C \rrbracket ?$
- $$\begin{aligned} &(((\llbracket C \rrbracket * \text{nd}_x) \cap v_x) * \text{nd}_y) \cap v_y \\ &= (\llbracket C \rrbracket * \text{nd}_x * \text{nd}_y) \cap v_x \cap v_y \end{aligned}$$
- $(P \wedge Q) * R = P * R \wedge Q * R$
(provided R is precise)

Communication

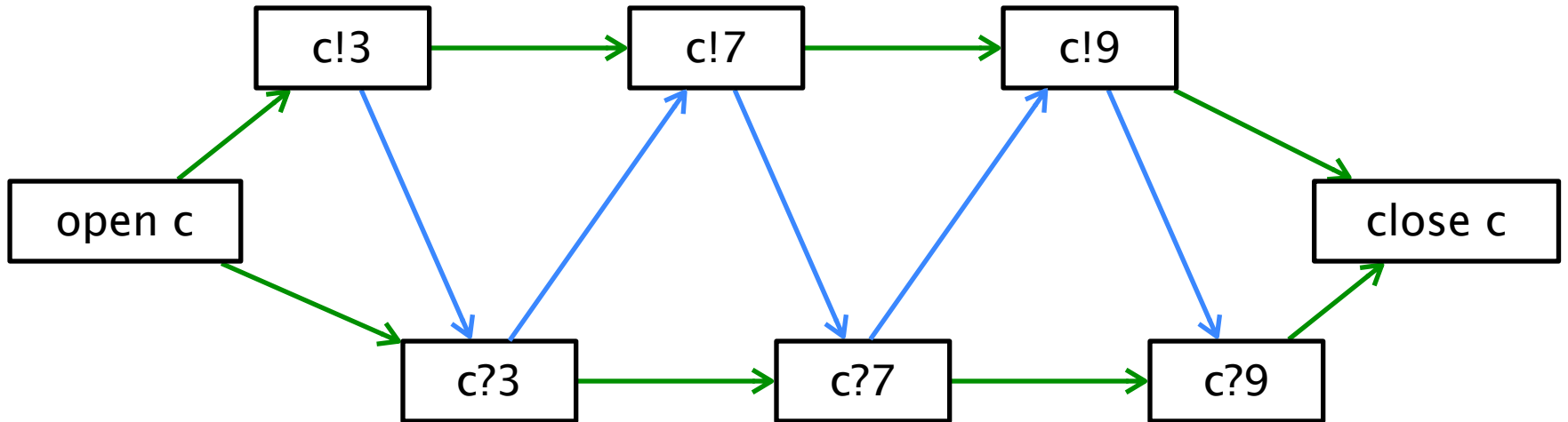
Well-behaved channel



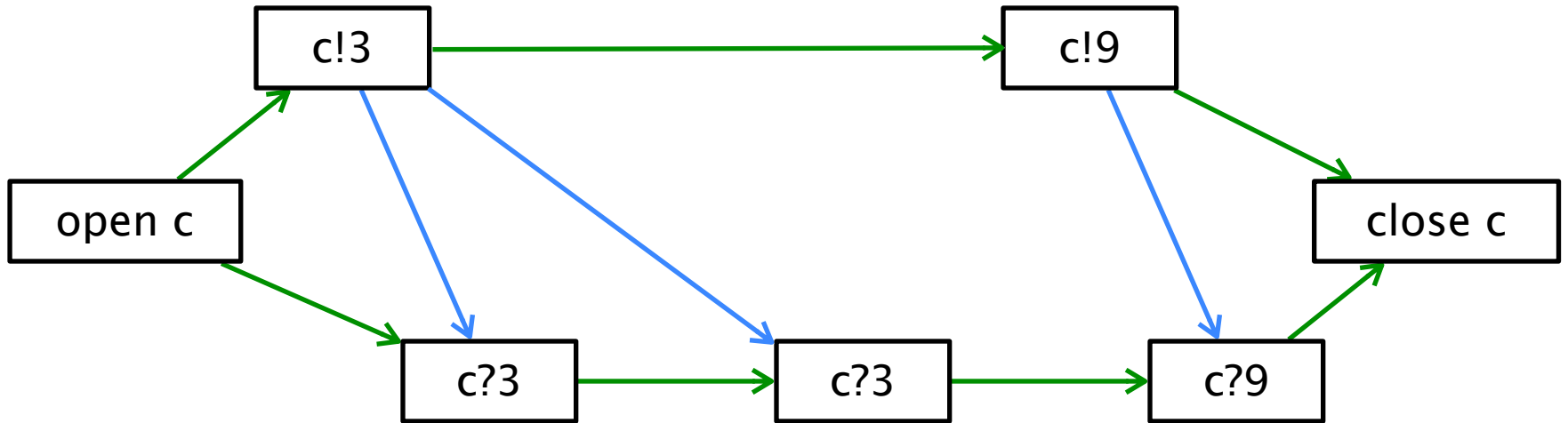
Lossy channel



Singly-buffered channel



Stuttering channel



Re-ordering channel

